# HAORAN HE

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# **EDUCATION**

## Hong Kong University of Science and Technology, Hong Kong

2024.2 - Present

Ph.D. student in Electronic and Computer Engineering

# Shanghai Jiao Tong University (SJTU), Shanghai, China

2019.9 - 2023.6

Bachelor's Degree in Computer Science (CS) GPA 3.88

# Interests

I am a second-year Ph.D. student at Hong Kong University of Science and Technology, advised by Prof. Ling Pan. I received my bachelor's Degree at Shanghai Jiao Tong University in June 2023, advised by Prof. Weinan Zhang and Prof. Yong Yu.

My research goal is to develop an intelligent decision-making system that possesses optimality, generalizability, interpretability, and robustness. To achieve this, I primarily focus on:

- Generalist Reinforcement Learning and its application in the real world.
- Generative models (e.g., flow and diffusion models) and their applications.
- Reinforcement learning for large foundation models (e.g., post-training).
- Large foundation models for reasoning and decision-making.

## **PUBLICATIONS**

See full list in my Google Scholar profile

- Random Policy Valuation is Enough for LLM Reasoning with Verifiable Rewards **Haoran He**, Yuxiao Ye, Qingpeng Cai, Chen Hu, Binxing Jiao, Daxin Jiang, Ling Pan. Preprint 2025, under review
- Scaling Image and Video Generation via Test-Time Evolutionary Search **Haoran He**, Jiajun Liang, Xintao Wang, Pengfei Wan, Di Zhang, Kun Gai, Ling Pan. Preprint 2025, under review
- Rectifying Reinforcement Learning for Reward Matching Haoran He, Emmanuel Bengio, Qingpeng Cai, Ling Pan. ICML 2025
- Task-Agnostic Pre-training and Task-Guided Fine-tuning for Versatile Diffusion Planner Chenyou Fan, Chenjia Bai, Zhao Shan, Haoran He, Yang Zhang, Zhen Wang. ICML 2025
- Pre-Trained Video Generative Models as World Simulators Haoran He, Yang Zhang, Liang Lin, Zhongwen Xu, Ling Pan ICLR 2025 World Model Workshop
- Looking Backward: Retrospective Backward Synthesis for Goal-Conditioned GFlowNets Haoran He, Can Chang, Huazhe Xu, Ling Pan ICLR 2025
- On the Value of Myopic Behavior in Policy Reuse Kang Xu, Chenjia Bai, Shuang Qiu, **Haoran He**, Bin Zhao, Zhen Wang, Wei Li, Xuelong Li. TPAMI 2025
- Learning an Actionable Discrete Diffusion Policy via Large-Scale Actionless Video Pre-Training Haoran He, Chenjia Bai, Ling Pan, Weinan Zhang, Bin Zhao, Xuelong Li.
  NeurIPS 2024
- Regularized Conditional Diffusion Model for Multi-Task Preference Alignment

Xudong Yu, Chenjia Bai, **Haoran He**, Changhong Wang, Xuelong Li. NeurIPS, 2024

- Bridging the Sim-to-Real Gap from the Information Bottleneck Perspective **Haoran He**, Peilin Wu, Chenjia Bai, Hang Lai, LingXiao Wang, Ling Pan, Xiaolin Hu, Weinan Zhang. CoRL, 2024, Oral
- SAM-E: Leveraging Visual Foundation Model with Sequence Imitation for Embodied Manipulation Junjie Zhang, Chenjia Bai, **Haoran He**, Wenke Xia, Zhigang Wang, Bin Zhao, Xiu Li, Xuelong Li. ICML 2024
- Robust Quadrupedal Locomotion via Risk-Averse Policy Learning Jiyuan Shi, Chenjia Bai, Haoran He, Lei Han, Dong Wang, Bin Zhao, Xiu Li, Xuelong Li. ICRA 2024
- Diffusion Model is an Effective Planner and Data Synthesizer for Multi-Task Reinforcement Learning Haoran He, Chenjia Bai, Kang Xu, Zhuoran Yang, Weinan Zhang, Dong Wang, Bin Zhao, Xuelong Li. NeurIPS 2023
- Diffusion Models for Reinforcement Learning: A Survey Zhengbang Zhu, Hanye Zhao, **Haoran He**, Yichao Zhong, Shenyu Zhang, Haoquan Guo, Tingting Chen, Weinan Zhang. TPAMI 2024 (under review)

# **EXPERIENCE**

## Intern at kuaishou Kling Team

Jan. 2025 – Present

Role: Research Intern

Brief introduction: Research on RL post-training for video foundation models. Advised by Dr. Xintao Wang.

- We are investigating the RL efficacy for fine-tuning video models to obtain better performance.
- We are trying to address problems that are challenging for simply scaling up model size and data size.

#### **Intern at Tencent AI Lab**

Sep. 2024 – Dec. 2024

Role: Research Intern

Brief introduction: Research on world models for policy generalization. Advised by Dr. Zhongwen Xu.

- We built a generalist video-based world model as an environmental simulator.
- We proposed DWS, an effective model-based RL algorithm to learn well-performed policies across different environments.

#### Intern at Shanghai AI Lab

Oct. 2022 – Feb. 2024

Role: Research Scientist Intern

Brief introduction: Research on generalist reinforcement learning and robotics. Advised by Dr. Chenjia Bai.

- Aims to master quadruped locomotion task via a novel RL method. Adversarial methods for domain adaptation(e.g. sim2real) and skill discovery for performance boosting are proven to be effective.
- Learn a single policy that can tackle multiple tasks from the collected offline data.
- Proposed a new model named MTDIFF, which is trained on large-scale datasets for multi-task decision-making.
- Proposed a new model named VPDD, which is a generalist video-based multi-task agent pre-trained on large-scale human videos.

#### PROFESSIONAL SERVICE

#### **Reviewers:**

- Conferences: ICML 2024-2025, IROS 2024, NeurIPS 2024, AAAI 2025, ICLR 2025, ICRA 2025
- Journals: IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)

## SKILLS

• Programming Languages: C == C++ == Python > Rust

- Platform: Linux, Mac, and Windows
- Tools: git for code management and ArcGis for geographic information system; Pytorch and Tensorflow for conducting machine learning experiments and designing neural networks
- Development: Machine learning, Reinforcement Learning, Data Analysis

# $\heartsuit$ Honors and Awards

1 <sup>st</sup> Prize in school robocup competition	2019
Merit Student in SJTU	2020
Cosco shipping scholarship	2020
Honorable Mention in Mathematical Contest In Modeling	2020
C-class Excellent Scholarship	2021
Merit Student in SJTU	2022
B-class Excellent Scholarship	2022
Hong Kong PostGraduate Scholarship	2024

## i Miscellaneous

- personal page: https://tinnerhrhe.github.io
- GitHub: https://github.com/tinnerhrhe
- Languages: English Fluent, Mandarin Native speaker
- Hobbies: Running, playing ping pong, and reading.